

# Characterization of Reachable Attractors using Petri Net Unfoldings

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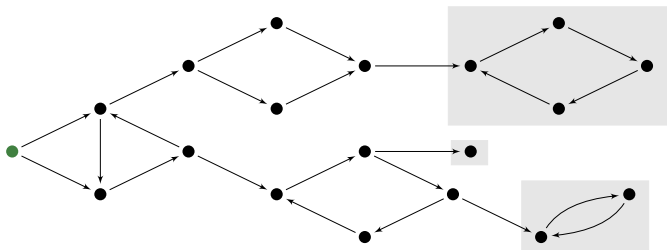
12th Conference on Computational Methods in Systems Biology  
17-19 November, 2014 - University of Manchester, UK

## Attractors in Discrete Dynamical Models

### Models

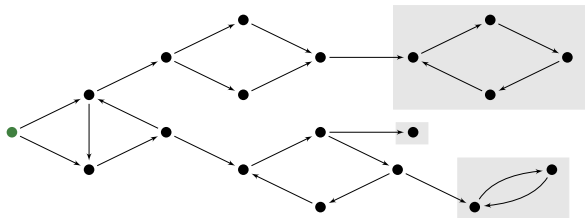
- Regulatory networks, signalling pathways
- Bio-chemical networks, ...

### Discrete Dynamics



### Attractors

- The “long term” dynamics (limit cycles / fixed points)
- Differentiation processes / homeostasis.



**Goal:** Exhaustive list of attractors reachable from a given state  
(one state of each attractor)

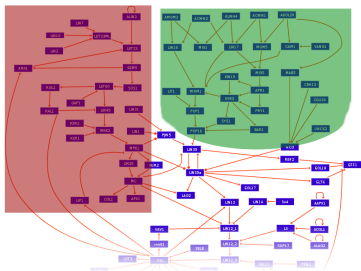
### Current approaches

- Explicit/**symbolic** computation of the state graph
- Problem is **inherently hard**: PSPACE-hard

*Alternatives:* approximations using simulations, heuristics w/ topology  
(non-exhaustive, no reachability constraint)

Exploit **concurrency** in networks

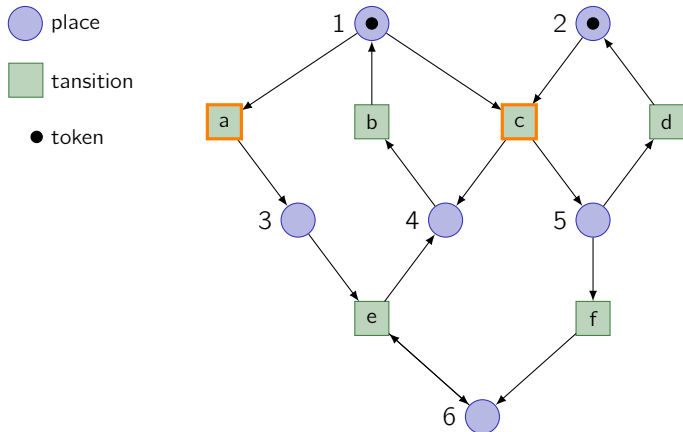
- Many components may evolve independently for a while
- $\Rightarrow$  generates multiple **spurious interleavings** in the state graph
- Many works in concurrency theory to tackle efficiently such dynamics (partial-order semantics)



## Contribution

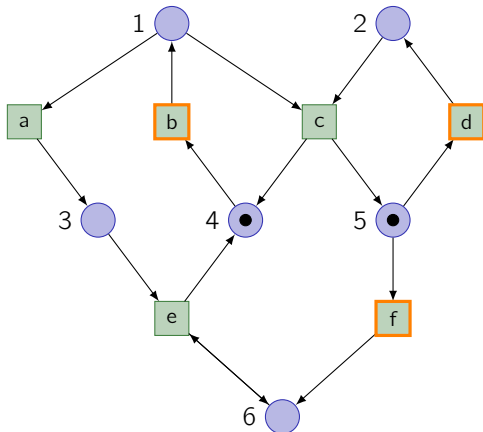
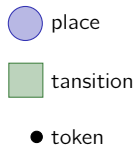
- New algorithm based on **Petri net unfoldings**
- **Complete characterization** of reachable attractors
- Applicable to **any safe Petri net**

## Safe Petri Net



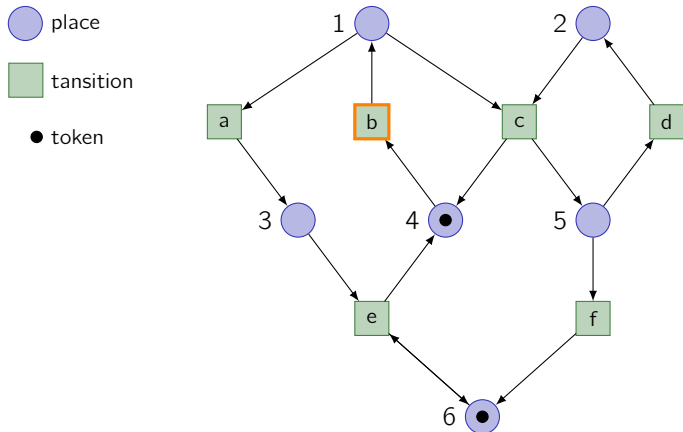
- **Safe** Petri net: at most one token per place
- Marking (state): set of places having one token
- Enabled transition: all (place) parents have one token
- Transition firing (one at a time): 1. empty tokens from parents, 2. add tokens to children

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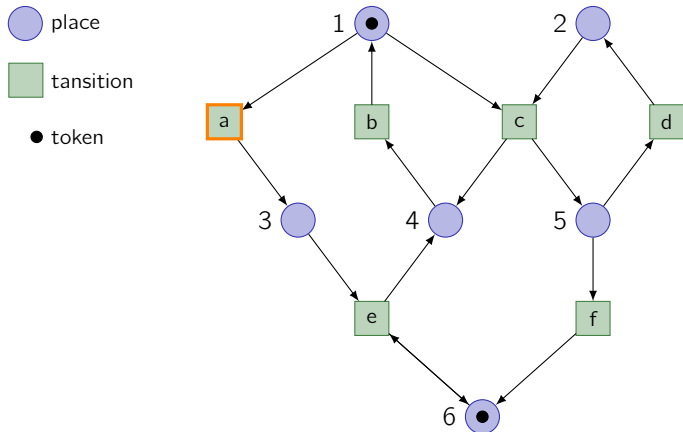
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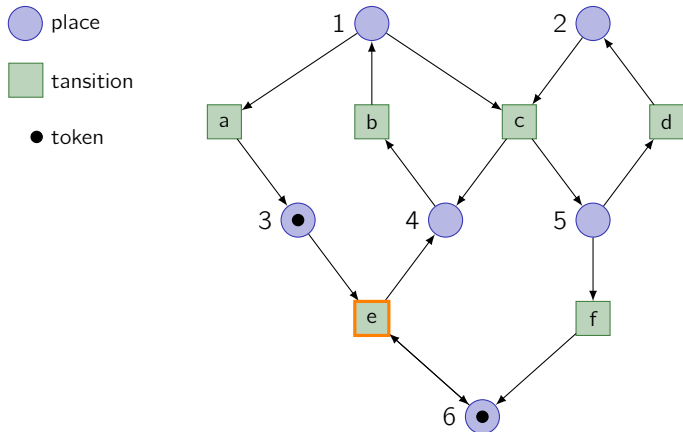
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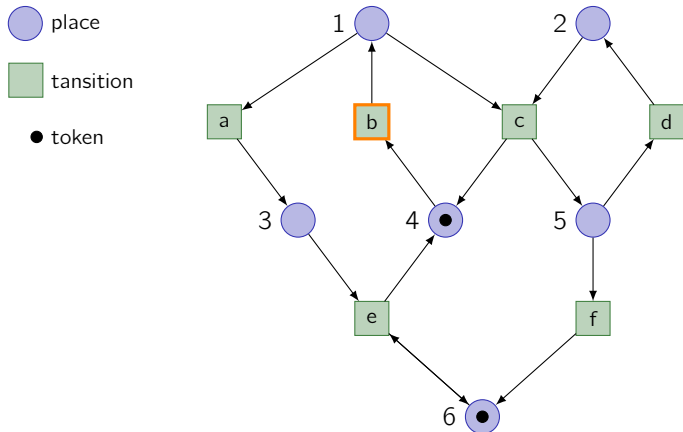


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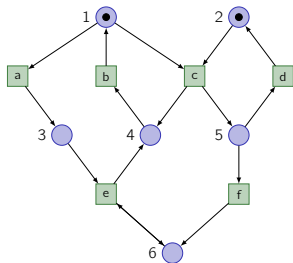
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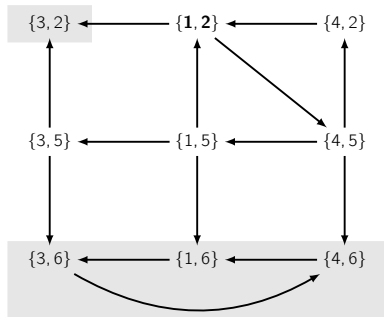
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## Reachable Attractors in Safe Petri Net

Petri net



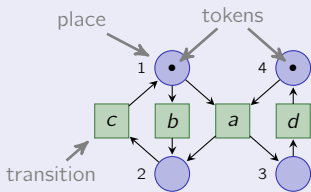
Marking graph



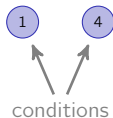
**Attractors** = Bottom Strongly Connected Components in the marking graph  
(from initial marking)

## Processes, Branching Processes and Unfoldings

Petri net:

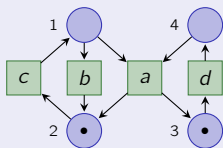


**Process:** representation of a non-sequential run as a partial order.

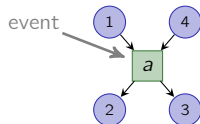


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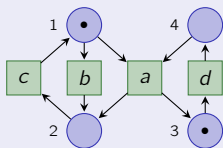


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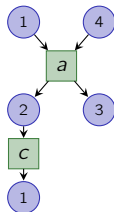


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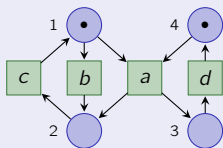


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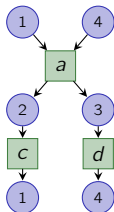


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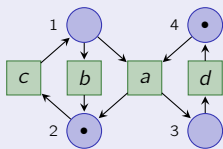


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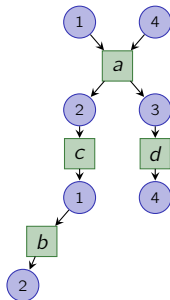


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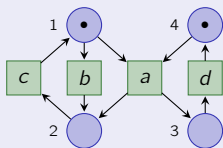
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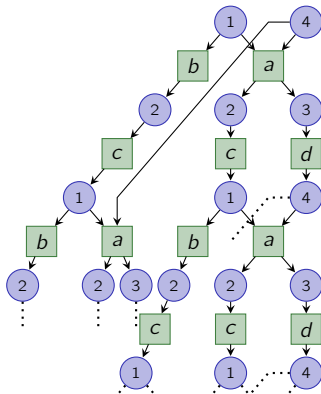
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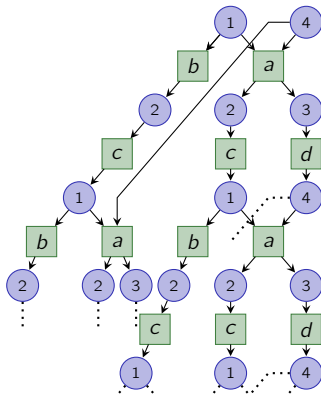
**Branching process:** representation of several runs.

**Unfolding:** maximal branching process.



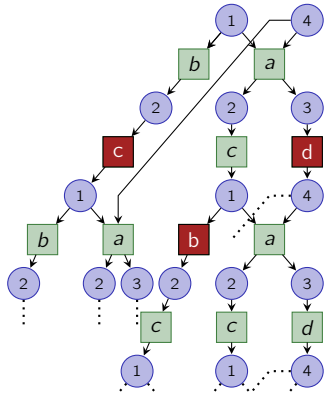
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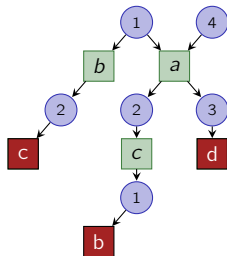


## Complete Finite Prefix of Unfolding

- Unfolding is an **infinite acyclic** net

### Complete Finite Prefix

- Prefix of the unfolding that contains **all** reachable markings
- When done with care:  
$$\text{size}(\text{prefix}) \leq \text{size}(\text{marking\_graph})$$
- Available tools: Mole<sup>1</sup>, Cunf<sup>2</sup>, ..



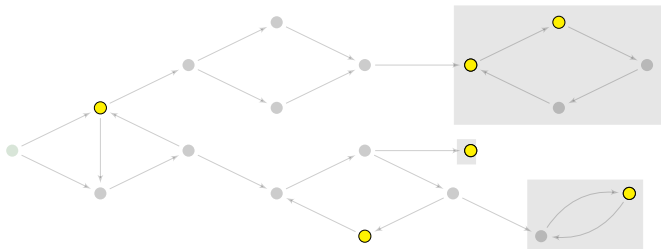
<sup>1</sup>: <http://www.lsv.ens-cachan.fr/~schwoon/tools/mole>

<sup>2</sup>: <https://code.google.com/p/cunf>

## Identify Attractors with Unfoldings

**General idea** given a safe Petri net with initial marking  $m_0$

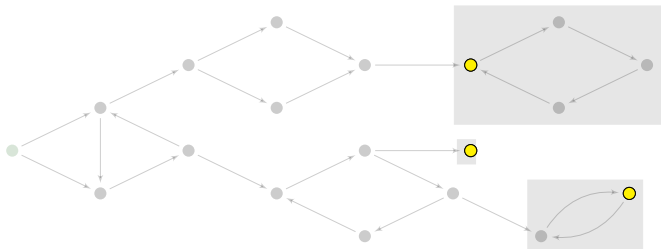
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- 2 Extract set of **markings intersecting all attractors**
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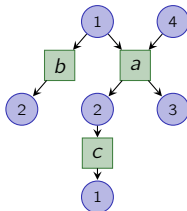


## From Complete Prefix to Maximal Configurations

### Maximal Configuration:

Marking led by a **maximal process** in the complete finite prefix

- Can be encoded as SAT.
- All attractors have at least one marking as max. conf.

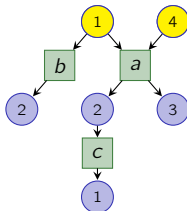


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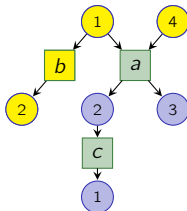


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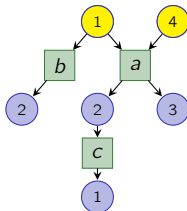


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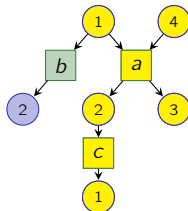


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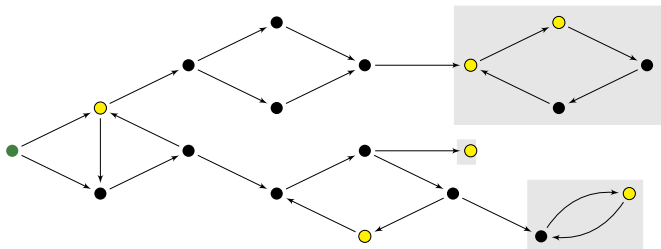
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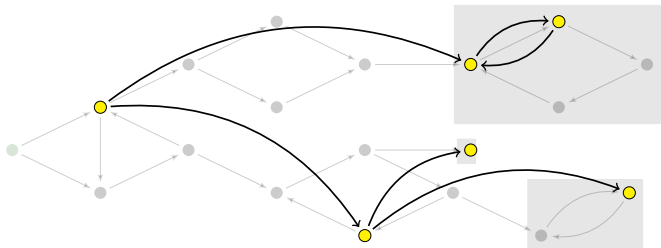
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Two max. conf.:  $\{2, 4\}$ ,  $\{1, 3\}$ .



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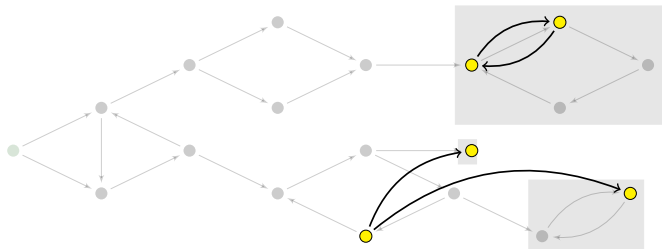
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  - ① if any marking in  $\mathcal{M}$  is reachable from  $m_i$  (e.g., using  $\mathcal{U}_i$ ):  
remove  $m_i$  from  $\mathcal{M}$ .

**Output**  $\mathcal{M}$

**Result:**

- **Each attractor reachable from  $m_0$  has one and only one marking in  $\mathcal{M}$**
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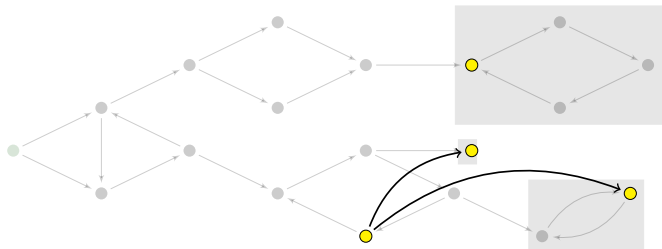
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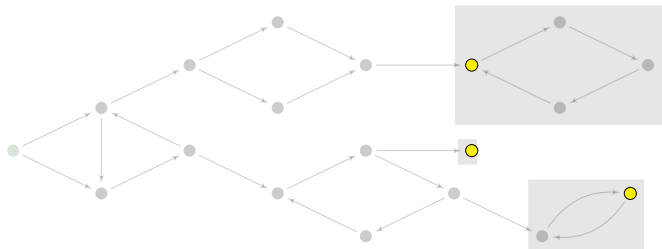
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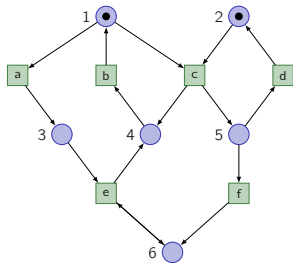
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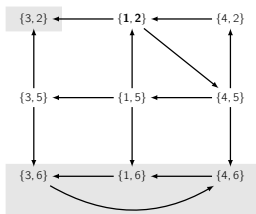
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## Small Example

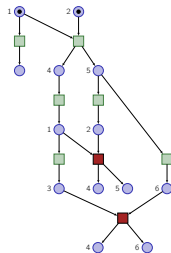
### 0. Petri net



### Marking graph

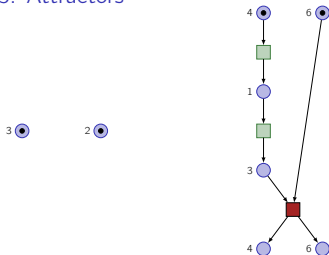


### 1. Complete Finite Prefix



### 2. Max. config.: $\{2, 3\}, \{4, 5\}, \{4, 6\}$

### 3. Attractors

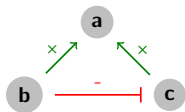




## Safe Petri Net Encoding of Discrete Networks

### Discrete Networks

- Set of variables with value in  $\mathbb{D} = \{0, \dots, l\}$  (Boolean or multi-valued)
- For each variable  $i$ ,  $f^i : \mathbb{D}^n \rightarrow \mathbb{D}$  (typically depends on a few other variables)



$$f^a(x) = x[b] \wedge x[c]$$

$$f^b(x) = 1$$

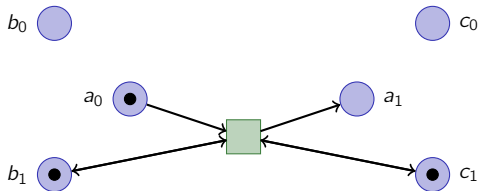
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### Encoding of asynchronous dynamics using safe Petri net

- One place per variable value
- Transitions for value changes

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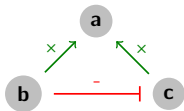
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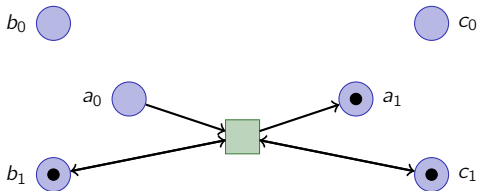
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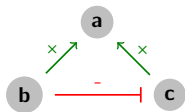
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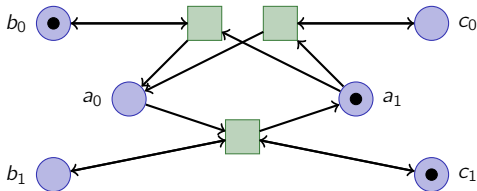
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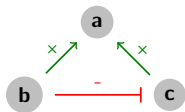
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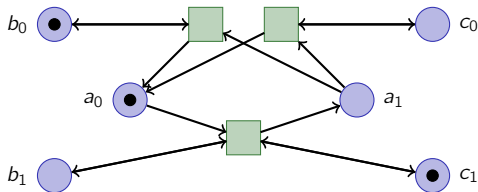
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- Transitions for value changes

$$f^a(x) = x[b] \wedge x[c]$$

- $a_0 \rightarrow a_1$  when  $b_1 \wedge c_1$
- $a_1 \rightarrow a_0$  when  $b_0$
- $a_1 \rightarrow a_0$  when  $c_0$



## Experiments

## Preliminary implementation

Model	nodes	reachable	prefix	max. conf.	attractors	time
Lambda switch	4	46	45	15	2	<1s
Cell cycle	10	112	111	34	1	<1s
ERBB	20	2,963	1,113	302	2	5s
VPC C. elegans	88	152,320	973	1,240	1	15min

## Remarks:

- In those examples, most of the time is spent in filtering max. conf.
- There may be many useless max. conf.
- Computing complete finite prefix may be not tractable.

**Goal:** Exhaustive list of attractors reachable from a given state  
(one state of each attractor)

### Proof of concept

- Relies on complete prefix of **unfolding of Petri nets**
- Exploits concurrency between transitions
- **Generic algorithm** for identifying all the reachable attractors

### On-going work for scalability

- More **constraints on candidate maximal configurations** (embed co-reachability constraints  $\rightarrow$  QBF)
- Iterative approach using **partial prefixes** of unfoldings.

### Further extensions

- Specialize to discrete/Boolean networks
- More efficient unfolding: symbolic, abstractions, ...

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Thank you for your attention.